

# Backward difference time discretization of parabolic equations on evolving surfaces

Christian Lubich  
Univ. Tübingen

joint work with Dhia Mansour (Tübingen)  
and Chandrasekhar Venkataraman (Warwick)

# Outline

---

Parabolic equations on evolving surfaces

Finite element space discretization

Backward difference time discretization

Stability and error bounds

Numerical experiment

# Outline

---

Parabolic equations on evolving surfaces

Finite element space discretization

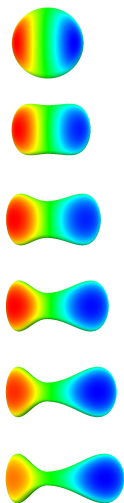
Backward difference time discretization

Stability and error bounds

Numerical experiment

## Diffusion on a sphere deforming to a baseball bat

---



## Notation: evolving surface

---

$\Gamma(t)$ , for  $t \in [0, T]$ , is a smoothly evolving family of smooth, compact  $d$ -dimensional **hypersurfaces** in  $\mathbb{R}^{d+1}$

$n = n(x, t)$  **normal vector** field to  $\Gamma(t)$

$v = v(x, t)$  **velocity** of the surface

## Notation: derivatives in time and space

---

material derivative of a function  $u = u(x, t)$ :

$$\dot{u} = \frac{\partial u}{\partial t} + v \cdot \nabla u.$$

tangential gradient: projection of the gradient to the tangent space

$$\nabla_{\Gamma} u = \nabla u - \nabla u \cdot n n$$

Laplace-Beltrami operator on  $\Gamma$  is the tangential divergence of the tangential gradient:

$$\Delta_{\Gamma} u = \nabla_{\Gamma} \cdot \nabla_{\Gamma} u.$$

## Linear parabolic equation on the evolving surface

---

conservation of a scalar quantity  $u = u(x, t)$ ,  $x \in \Gamma(t)$ ,  $t \in [0, T]$   
with a linear diffusive flux on  $\Gamma(t)$  is modelled by

$$\dot{u} + u \nabla_{\Gamma} \cdot \nu - \Delta_{\Gamma} u = f \quad \text{on } \Gamma$$

## Weak formulation

---

$$\frac{d}{dt} \int_{\Gamma} u \varphi + \int_{\Gamma} \nabla_{\Gamma} u \cdot \nabla_{\Gamma} \varphi = \int_{\Gamma} u \dot{\varphi} + \int_{\Gamma} f \varphi$$

for all smooth  $\varphi = \varphi(x, t)$ ,  $x \in \Gamma(t)$ ,  $t \in [0, T]$

obtained via Leibniz formula

$$\frac{d}{dt} \int_{\Gamma} g = \int_{\Gamma} \dot{g} + g \nabla_{\Gamma} \cdot \nu$$



# Outline

---

Parabolic equations on evolving surfaces

**Finite element space discretization**

Backward difference time discretization

Stability and error bounds

Numerical experiment

## Surface discretization

---

surface triangulation  $\Gamma_h(t) = \bigcup_{T(t) \in \mathcal{T}(t)} T(t)$

with simplices  $T(t)$  having vertices  $a_i(t) \in \Gamma(t)$

piecewise linear nodal basis functions:  $\phi_j(a_i(t), t) = \delta_{ji}$

finite element space  $S_h(t) = \text{span}\{\phi_1(\cdot, t), \dots, \phi_N(\cdot, t)\}$

discrete velocity  $v_h(x, t) = \sum_{j=1}^N v(a_j(t), t) \phi_j(x, t)$

## Discrete-surface derivatives

---

discrete material derivative on the discrete evolving surface:

$$\dot{u}_h = \frac{\partial u_h}{\partial t} + v_h \cdot \nabla u_h$$

key property of basis functions:

$$\dot{\phi}_i = 0$$

discrete surface gradient (understood in a piecewise sense):

$$\nabla_{\Gamma_h} u_h = \nabla u_h - \nabla u_h \cdot n_h n_h.$$

## Finite element discretization of the parabolic PDE

---

$$\frac{d}{dt} \int_{\Gamma_h} u_h \varphi_h + \int_{\Gamma_h} \nabla_{\Gamma_h} u_h \cdot \nabla_{\Gamma_h} \varphi_h = \int_{\Gamma_h} u_h \dot{\varphi}_h + \int_{\Gamma_h} f_h \varphi_h \quad \forall \varphi_h \in S_h(t).$$

system of ODEs for nodal values  $u(t) = (u_i(t))$ :

$$\frac{d}{dt} (M(t)u(t)) + A(t)u(t) = f(t)$$

with mass and stiffness matrices

$$M(t)_{ij} = \int_{\Gamma_h(t)} \phi_i(\cdot, t) \phi_j(\cdot, t),$$
$$A(t)_{ij} = \int_{\Gamma_h(t)} \nabla_{\Gamma_h(t)} \phi_i(\cdot, t) \cdot \nabla_{\Gamma_h(t)} \phi_j(\cdot, t)$$

# Outline

---

Parabolic equations on evolving surfaces

Finite element space discretization

Backward difference time discretization

Stability and error bounds

Numerical experiment

# BDF

---

With step size  $\tau > 0$ , discretize

$$\frac{1}{\tau} \sum_{j=0}^k \delta_j M(t_{n-j}) u_{n-j} + A(t_n) u_n = f(t_n), \quad n \geq k,$$

for given starting values  $u_0, \dots, u_{k-1}$ .

Method coefficients  $\delta_j$  are given by

$$\delta(\zeta) = \sum_{j=0}^k \delta_j \zeta^j = \sum_{\ell=1}^k \frac{1}{\ell} (1 - \zeta)^\ell.$$

Order  $k$ , 0-stable for  $k \leq 6$ .

## Lemma from Dahlquist's G-stability theory (1978)

---

Let  $\delta(\zeta)$  and  $\mu(\zeta)$  be polynomials of degree at most  $k$ . Let  $\langle \cdot, \cdot \rangle$  be an inner product on  $\mathbb{R}^N$  with associated norm  $|\cdot|$ . If

$$\operatorname{Re} \frac{\delta(\zeta)}{\mu(\zeta)} > 0 \quad \text{for } |\zeta| < 1,$$

then there exists a symmetric positive definite matrix  $(g_{ij}) \in \mathbb{R}^{k \times k}$  such that for all  $v_0, \dots, v_k \in \mathbb{R}^N$

$$\left\langle \sum_{i=0}^k \delta_i v_{k-i}, \sum_{j=0}^k \mu_j v_{k-j} \right\rangle \geq \sum_{i,j=1}^k g_{ij} \langle v_i, v_j \rangle - \sum_{i,j=1}^k g_{ij} \langle v_{i-1}, v_{j-1} \rangle.$$

## Lemma from Nevanlinna & Odeh (1981)

---

If  $k \leq 5$ , then there exists  $0 \leq \eta < 1$  such that for

$$\delta(\zeta) = \sum_{\ell=1}^k \frac{1}{\ell} (1 - \zeta)^\ell,$$

$$\operatorname{Re} \frac{\delta(\zeta)}{1 - \eta\zeta} > 0 \quad \text{for } |\zeta| < 1.$$

---

The smallest possible value of  $\eta$  is found to be  
 $\eta = 0, 0, 0.0836, 0.2878, 0.8160$  for  $k = 1, \dots, 5$ .



# Outline

---

Parabolic equations on evolving surfaces

Finite element space discretization

Backward difference time discretization

**Stability and error bounds**

Numerical experiment

## Defects and errors

---

The ODE solution satisfies the BDF relation up to a defect  $d_n$ :

$$\frac{1}{\tau} \sum_{j=0}^k \delta_j M(t_{n-j}) u(t_{n-j}) + A(t_n) u(t_n) = f(t_n) - d_n.$$

For smooth solutions we have by Taylor expansion (in suitable norms!)  $d_n = \mathcal{O}(\tau^k)$ . The error

$$e_n = u_n - u(t_n)$$

then satisfies the [error equation](#)

$$\frac{1}{\tau} \sum_{j=0}^k \delta_j M(t_{n-j}) e_{n-j} + A(t_n) e_n = d_n, \quad n \geq k.$$

## Time-dependent norms and semi-norms

---

We work with the norm, for  $w = (w_i)$  and  $w_h(t) = \sum_i w_i \phi_i(\cdot, t)$ ,

$$|w|_t^2 = w^T M(t) w = \int_{\Gamma_h(t)} w_h(t)^2$$

and the semi-norm

$$\|w\|_t^2 = w^T A(t) w = \int_{\Gamma_h(t)} |\nabla_{\Gamma_h(t)} w_h(t)|^2$$

Basic inequalities:

$$\begin{aligned} w^T (M(s) - M(t)) z &\leq \mu |s - t| |w|_t |z|_t \\ w^T (A(s) - A(t)) z &\leq \kappa |s - t| \|w\|_t \|z\|_t \end{aligned}$$

for all  $w, z \in \mathbb{R}^N$  and  $0 \leq s, t \leq T$ .

# Stability

---

For the  $k$ -step BDF method with  $k \leq 5$ ,

$$|e_n|_{t_n}^2 + \tau \sum_{j=k}^n \|e_j\|_{t_j}^2 \leq C \tau \sum_{j=k}^n \|d_j\|_{*,t_j}^2 + C \max_{0 \leq i \leq k-1} |e_i|_{t_i}^2$$

where  $\|w\|_{*,t}^2 = w^T (A(t) + M(t))^{-1} w$ .

$C$  depends on  $\mu, \kappa, T$ , but is independent of the spatial grid size  $h$ .

## Stability: sketch of proof

---

Rewrite the error equation as

$$M_n \sum_{j=0}^k \delta_j e_{n-j} + \tau A_n e_n = \tau d_n + \sum_{j=1}^k \delta_j (M_n - M_{n-j}) e_{n-j}$$

and take the inner product with  $e_n - \eta e_{n-1}$ .

Use

- ▶ the results by Dahlquist and Nevanlinna & Odeh,
- ▶ the norm inequalities,
- ▶ standard estimates like Cauchy-Schwarz and Young inequality.

## Error bound

---

Let  $P_h(t)$  be the Ritz projection to the ESFEM space at time  $t$ .

The error  $e_h^n = u_h^n - P_h(t_n)u(t_n)$  is bounded for  $t_n \leq T$  by

$$\begin{aligned} & \max_{k \leq j \leq n} \|e_h^j\|_{L_2(\Gamma_h(t_j))} + \left( \tau \sum_{j=k}^n \|\nabla_{\Gamma_h(t_j)} e_h^j\|_{L_2(\Gamma_h(t_j))}^2 \right)^{1/2} \\ & \leq C\tau^k + Ch^2. \end{aligned}$$

# Outline

---

Parabolic equations on evolving surfaces

Finite element space discretization

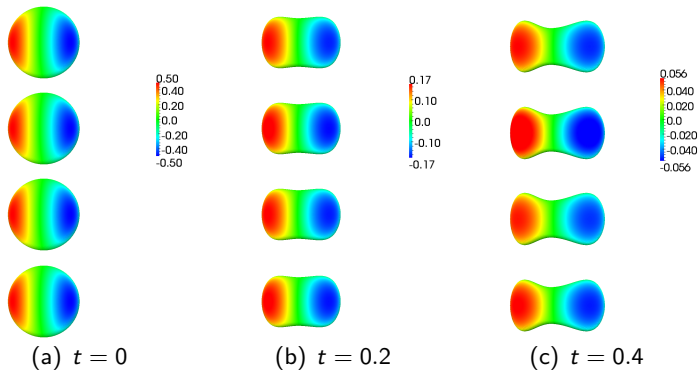
Backward difference time discretization

Stability and error bounds

**Numerical experiment**

# Numerical experiment

---

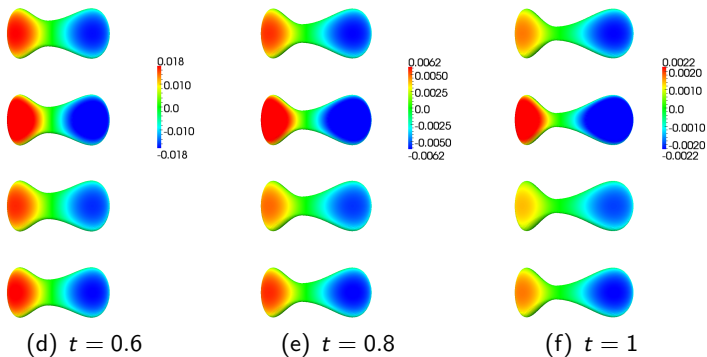


Reference solution and BDF of orders 1,2,4 with  $\tau = 0.05$



# Numerical experiment

---



Reference solution and BDF of orders 1,2,4 with  $\tau = 0.05$

# Outline

---

Parabolic equations on evolving surfaces

Finite element space discretization

Backward difference time discretization

Stability and error bounds

Numerical experiment