

Operator splitting for delay equations

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joint with

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$$\begin{cases} \dot{u}(t) = Bu(t) + g(u(t-1)) \\ u(0, s) = f(s), \quad s \in [-1, 0] \quad f : [-1, 0] \rightarrow H \text{ given initial function} \end{cases}$$

□ H Hilbert space, $B : D(B) \rightarrow H$ linear, $g : H \rightarrow H$ function

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History function:

$$u_t : [-1, 0] \rightarrow H, u_t(\sigma) := \begin{cases} u(t + \sigma) & t + \sigma \geq 0 \\ f(t + \sigma) \end{cases}$$

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$$\begin{cases} \dot{u}(t) = Bu(t) + g(\Phi u_t) \\ u_0 = f \end{cases}$$

□ $\Phi v = \delta_{-1} v$

point delay

or more generally

□ $\Phi v = \int_{-1}^0 v(\sigma) d\eta(\sigma)$

with $\eta \in \text{BV}([-1, 0]; \mathcal{L}(H))$

Cauchy problem:

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time step: $h = \frac{t}{n}$

1st step $\left\{ \begin{array}{l} \text{Solve problem } \dot{v}(t) = \Psi v_t \text{ with } v_0 = f \\ \text{Solve problem } \dot{w}(t) = Bw(t) \text{ with } w(0) = v(h) \end{array} \right.$

2nd step $\left\{ \begin{array}{l} \text{Solve problem } \dot{v}(t) = \Psi v_t \text{ with } v_h = w_h \\ \text{Solve problem } \dot{w}(t) = Bw(t) \text{ with } w(h) = v(2h) \end{array} \right.$

Cauchy problem:

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⋮

Iterate this procedure for n steps

⋮

$$n^{\text{th}} \text{ step} \begin{cases} \text{Solve problem } \dot{v}(t) = \Psi v_t \text{ with } v_{(n-1)h} = w_{(n-1)h} \\ \text{Solve problem } \dot{w}(t) = Bw(t) \text{ with } w((n-1)h) = v(nh) \end{cases}$$

$\rightsquigarrow u^{\text{sp}}(t)$ the **splitting-solution** at time-level t

G. Webb, A. Bátkai–S. Piazzera:

□ $\mathcal{E} := H \times L^p([-1, 0]; H)$

new state space

□ and the new unknown function as

$$t \mapsto \mathcal{U}(t) := \begin{pmatrix} u(t) \\ u_t \end{pmatrix} \in \mathcal{E}.$$

Then the delay equation takes the form of an abstract Cauchy problem on the space \mathcal{E}

$$\begin{cases} \dot{\mathcal{U}}(t) = \mathcal{G}\mathcal{U}(t), & t \geq 0, \\ \mathcal{U}(0) = \begin{pmatrix} x \\ f \end{pmatrix} \in \mathcal{E}, \end{cases}$$

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$$\mathcal{G} := \begin{pmatrix} B & \Psi \\ 0 & \frac{d}{d\sigma} \end{pmatrix} \quad \text{with} \quad D(\mathcal{G}) := \left\{ \begin{pmatrix} x \\ f \end{pmatrix} \in D(B) \times W^{1,p}([-1, 0]; H) : f(0) = x \right\}$$

□ generates a semigroup (dynamical system) \mathcal{S}

$$\mathcal{S}(t)\mathcal{S}(s) = \mathcal{S}(t+s), \quad \mathcal{S}(0) = I$$

□ the solution is

$$\mathcal{U}(t) = \mathcal{S}(t) \begin{pmatrix} x \\ f \end{pmatrix} \quad \text{for} \quad \begin{pmatrix} x \\ f \end{pmatrix} \in D(\mathcal{G})$$

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Splitting Type 1

$$\mathcal{G} := \begin{pmatrix} B & \Psi \\ 0 & \frac{d}{d\sigma} \end{pmatrix} = \begin{pmatrix} B & 0 \\ 0 & 0 \end{pmatrix} + \begin{pmatrix} 0 & \Psi \\ 0 & \frac{d}{d\sigma} \end{pmatrix} = \mathcal{A}_0 + \mathcal{A}_d$$

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Splitting Type 2

$$\mathcal{G} := \begin{pmatrix} B & \Psi \\ 0 & \frac{d}{d\sigma} \end{pmatrix} = \begin{pmatrix} B & 0 \\ 0 & \frac{d}{d\sigma} \end{pmatrix} + \begin{pmatrix} 0 & \Psi \\ 0 & 0 \end{pmatrix} = \mathcal{B}_d + \mathcal{B}_0$$

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Then:

□ $\mathcal{G}, \mathcal{A}_d, \mathcal{A}_0$ are generators of quasi-contraction semigroups, $\mathcal{U}, \mathcal{S}_d, \mathcal{S}_0$

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Then:

- $\mathcal{G}, \mathcal{A}_d, \mathcal{A}_0$ are generators of quasi-contraction semigroups, $\mathcal{U}, \mathcal{S}_d, \mathcal{S}_0$
- The sequential splitting converges:

$$\mathcal{U}(t) \begin{pmatrix} x \\ f \end{pmatrix} = \lim_{n \rightarrow \infty} \left[\mathcal{S}_0 \left(\frac{t}{n} \right) \mathcal{S}_d \left(\frac{t}{n} \right) \right]^n \begin{pmatrix} x \\ f \end{pmatrix}.$$

Theorem: [E. Hansen, A. Ostermann]

- H Hilbert space
- A, B generate contraction C_0 -semigroups T_0, T_1 on H
- $G = \overline{A_0 + A_1}$ generates a semigroup T and satisfies

$$D(G^2) \subset D(A_0A_1)$$

$$\implies \|T_0(h)T_1(h)x - T(h)x\| \leq C \cdot h^2 \cdot \|x\|_{G^2} \quad \text{for all } x \in D(G^2)$$

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Application to delay equations

Suppose:

- B generates a contraction semigroup, $g(x) = x$
- $\text{ran } \Phi \subset D(B)$

$$\implies \|\mathcal{S}_0(h)\mathcal{S}_d(h)x - \mathcal{S}(h)x\| \leq C \cdot h^2 \cdot \left\| \begin{pmatrix} x \\ f \end{pmatrix} \right\|_{\mathcal{G}^2} \quad \text{for all } \begin{pmatrix} x \\ f \end{pmatrix} \in D(\mathcal{G}^2)$$

Suppose:

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Need: $D(\mathcal{G}^2) \subseteq D(\mathcal{A}_0 \mathcal{A}_d)$

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$$\implies \quad D(\mathcal{G}^2) \subset D(\mathcal{G}) \subset D(\mathcal{A}_d) = D(\mathcal{A}_0\mathcal{A}_d), \quad \checkmark$$

□ $\Phi(v) = \delta_{-1}v$ (point delay)

$$\Phi(v) = \int_{-1}^0 v(\sigma) d\eta(\sigma)$$

□ $\Phi : W^{1,p}([1, 0]; H) \rightarrow H$

Drawbacks:

1. $\text{ran } \Phi \subseteq D(B)$ is too strong!!!!

point delays are excluded!

$$\square \quad \Phi(v) = \delta_{-1}v \quad (\text{point delay}) \quad \Phi(v) = \int_{-1}^0 v(\sigma) d\eta(\sigma)$$

$$\square \quad \Phi : W^{1,p}([1, 0]; H) \rightarrow H$$

Drawbacks:

1. $\text{ran } \Phi \subseteq D(B)$ is too strong!!!!

point delays are excluded!

2. Too strong and unnatural compatibility conditions are needed:

$$D(\mathcal{G}^2) = \left\{ \begin{pmatrix} x \\ f \end{pmatrix} \in D(B) \times W^{2,p}([-1, 0]; H) : f(0) = x, f'(0) = Bx + \Phi f \in D(B) \right\}.$$

$\begin{pmatrix} x \\ f \end{pmatrix} \in D(\mathcal{G}^2)$ means:

$$\square \quad f(0) = x$$

$$\square \quad \text{AND } Bx + \Phi f = f'(0) \text{ ????$$

Theorem: [A. Bátkai, P. Csomós, B.F.]

Suppose:

- $p \geq 1$, B generates a linear contraction semigroup in the Hilbert space H
- $\eta : [-1, 0] \rightarrow \mathcal{L}(H)$ Lipschitz near 0
- Φ maps $D(B)$ valued function into $D(B)$
- g is Lipschitz in H and $D(B)$

Let

$$\begin{pmatrix} x \\ f \end{pmatrix} \in \mathcal{D} := \left\{ \begin{pmatrix} x \\ f \end{pmatrix} \in D(B^2) \times W^{1,p}([-1, 0]; D(B)), f \in \text{Lip}([-1, 0]; H), f(0) = x \right\}.$$

\implies

For all $t_{\max} > 0$ there is a constant $C > 0$ such that

$$\left\| \left((\mathcal{S}_0(\tfrac{t}{n}) \mathcal{S}_d(\tfrac{t}{n}))^n - \mathcal{S}(t) \right) \begin{pmatrix} x \\ f \end{pmatrix} \right\| \leq \frac{C}{n} \left\| \begin{pmatrix} x \\ f \end{pmatrix} \right\|_{\mathcal{D}} \quad \text{for all } t \in [0, t_{\max}],$$

for all $\begin{pmatrix} x \\ f \end{pmatrix} \in \mathcal{D}$.

“First order convergence”

Where:

$$\left\| \begin{pmatrix} x \\ f \end{pmatrix} \right\|_{\mathcal{D}} := \|x\|_B + \|Bx\|_B + \|f\|_{W^{1,p}(D(B))} + \|f\|_{\text{Lip}(H)}.$$

- ❑ \mathcal{D} is invariant under \mathcal{S}
- ❑ Local error analysis for $\begin{pmatrix} x \\ f \end{pmatrix} \in \mathcal{D}$
- ❑ Standard telescopic argument
“stability + local error estimates \implies global error estimates”

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Telescopic summation:

$$\begin{aligned}
 & \left(\mathcal{S}_0\left(\frac{t}{n}\right) \mathcal{S}_d\left(\frac{t}{n}\right) \right)^n - \mathcal{S}(t) \\
 &= \sum_{k=0}^{n-1} \left(\left(\mathcal{S}_0\left(\frac{t}{n}\right) \mathcal{S}_d\left(\frac{t}{n}\right) \right)^{n-k} \underbrace{\mathcal{S}_0\left(\frac{t}{n}\right) \mathcal{S}_d\left(\frac{t}{n}\right) \mathcal{S}\left(\frac{kt}{n}\right) - \left(\mathcal{S}_0\left(\frac{t}{n}\right) \mathcal{S}_d\left(\frac{t}{n}\right) \right)^{n-k} \mathcal{S}\left(\frac{t}{n}\right) \mathcal{S}\left(\frac{kt}{n}\right)}_{\text{gives the local error}} \right).
 \end{aligned}$$

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 \end{aligned}$$

$$\left\| \left(\mathcal{S}_0\left(\frac{t}{n}\right) \mathcal{S}_d\left(\frac{t}{n}\right) \right)^n - \mathcal{S}(t) \right\|_{\mathcal{E}} \begin{pmatrix} x \\ f \end{pmatrix} \leq \sum_{k=0}^{n-1} K \left(\frac{t}{n}\right)^2 \left(1 + \left\| \mathcal{S}\left(\frac{kt}{n}\right) \begin{pmatrix} x \\ f \end{pmatrix} \right\|_{\mathcal{D}} \right) \leq \frac{C}{n} \left(1 + \left\| \mathcal{S}\left(\frac{kt}{n}\right) \begin{pmatrix} x \\ f \end{pmatrix} \right\|_{\mathcal{D}} \right)$$

Invariance of

$$\mathcal{D} := \left\{ \begin{pmatrix} x \\ f \end{pmatrix} \in D(B^2) \times W^{1,p}([-1, 0]; D(B)), f \in \text{Lip}([-1, 0]; H), f(0) = x \right\}.$$

under the unsplit problem \mathcal{S} .

For the proof:

- Lipschitz continuity for solutions of nonlinear dissipative problems
- Lipschitz continuity of η (the delay term)

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Local error

There is a constant $K > 0$ such that for all $h \geq 0$ we have

$$\left\| \mathcal{S}_0(t) \mathcal{S}_d(h) \begin{pmatrix} x \\ f \end{pmatrix} - \mathcal{S}(h) \begin{pmatrix} x \\ f \end{pmatrix} \right\|_{\mathcal{E}} \leq Kh^2 \left\| \begin{pmatrix} x \\ f \end{pmatrix} \right\|_{\mathcal{D}} \quad \text{for all } \begin{pmatrix} x \\ f \end{pmatrix} \in \mathcal{D}.$$

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- Lipschitz continuity of η (the delay term)

Local error

There is a constant $K > 0$ such that for all $h \geq 0$ we have

$$\left\| \mathcal{S}_0(t) \mathcal{S}_d(h) \begin{pmatrix} x \\ f \end{pmatrix} - \mathcal{S}(h) \begin{pmatrix} x \\ f \end{pmatrix} \right\|_{\mathcal{E}} \leq Kh^2 \left\| \begin{pmatrix} x \\ f \end{pmatrix} \right\|_{\mathcal{D}} \quad \text{for all } \begin{pmatrix} x \\ f \end{pmatrix} \in \mathcal{D}.$$

For the proof:

- structure of \mathcal{S}_d and \mathcal{S}_0
- variation of constants formula

Nonautonomous delay equation:

$$\begin{cases} \dot{u}(t) = B(t)u(t) + \Phi(t)u_t \\ u_0 = f \end{cases}$$

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□ $B(s) \in \mathcal{L}(H)$ and generates $V^{(s)}$ on X .

□ $\Phi(s) : L^1([-1, 0]; X) \rightarrow X$ are bounded for all $s \in \mathbb{R}$.

□ $s \mapsto B(s)x$ is bounded and locally Lipschitz continuous, i.e., for all $T_0 > 0$ there is $L_{T_0} \geq 0$ with

$$\|B(s)x - B(t)x\| \leq L_{T_0}\|x\||t - s|$$

for all $|t|, |s| \leq T_0$.

□ $s \mapsto \Phi(s)f$ is bounded and locally Lipschitz continuous, i.e., for all $T_0 > 0$ there is $L_{T_0} \geq 0$ with

$$\|\Phi(s)f - \Phi(t)f\| \leq L_{T_0}\|f\|_1|t - s|$$

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$$\mathcal{G}(t) := \begin{pmatrix} B(t) & \Phi(t) \\ 0 & \frac{d}{d\sigma} \end{pmatrix} = \begin{pmatrix} B(t) & 0 \\ 0 & \frac{d}{d\sigma} \end{pmatrix} + \begin{pmatrix} 0 & \Psi(t) \\ 0 & 0 \end{pmatrix} = \mathcal{B}_d(t) + \mathcal{B}_0(t)$$

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Then:

the following problems are **well-posed**:

- $\dot{\mathcal{V}}(t) = \mathcal{B}_0(s)\mathcal{V}(t), t \geq 0$ \rightsquigarrow semigroup $\mathcal{T}_0^{(s)}$
- $\dot{\mathcal{W}}(t) = \mathcal{B}_d(s)\mathcal{W}(t), t \geq 0$ \rightsquigarrow semigroup $\mathcal{T}_d^{(s)}$
- $\dot{\mathcal{U}}(t) = \mathcal{G}(t)\mathcal{U}(t), t \geq s$ \rightsquigarrow evolution family \mathcal{T}

$$\mathcal{T}(t, s) = \mathcal{T}(t, r)\mathcal{T}(r, s), \mathcal{T}(s, s) = I \text{ for all } s \leq r \leq t$$

Suppose the equations are **autonomous**

$$\mathcal{G} := \begin{pmatrix} B & \Psi \\ 0 & \frac{d}{d\sigma} \end{pmatrix} \quad \text{with} \quad D(\mathcal{G}) := \left\{ \begin{pmatrix} x \\ f \end{pmatrix} \in H \times W^{1,1}([-1, 0]; H) : f(0) = x \right\}$$

$$\mathcal{B}_d := \begin{pmatrix} 0 & \Psi \\ 0 & 0 \end{pmatrix} \quad \text{with} \quad D(\mathcal{B}_d) := H \times L^1([-1, 0]; H)$$

$$\mathcal{B}_0 := \begin{pmatrix} B & 0 \\ 0 & \frac{d}{d\sigma} \end{pmatrix} \quad \text{with} \quad D(\mathcal{B}_d) := \left\{ \begin{pmatrix} x \\ f \end{pmatrix} \in H \times W^{1,1}([-1, 0]; H) : f(0) = x \right\}$$

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Commutator bounds [cf. T. Jahnke, Ch. Lubich]???

$$\begin{aligned} D(\mathcal{B}_0 \mathcal{B}_d) &= \left\{ \begin{pmatrix} x \\ f \end{pmatrix} : \mathcal{B}_d \begin{pmatrix} x \\ f \end{pmatrix} \in D(\mathcal{B}_0) \right\} = \left\{ \begin{pmatrix} x \\ f \end{pmatrix} : \begin{pmatrix} \Phi f \\ 0 \end{pmatrix} \in D(\mathcal{B}_0) \right\} \\ &= \left\{ \begin{pmatrix} x \\ f \end{pmatrix} : \Phi f = 0 \right\} \end{aligned}$$

$$D(\mathcal{B}_d \mathcal{B}_0) = D(\mathcal{B}_0)$$

\implies very bad commutator properties!!!

abstract results are not applicable

Theorem: [A. Bátkai, P. Csomós, B. F.]

For every $T_0 > 0$ there is constant $C > 0$ such that for all $f \in W^{1,1}([-1, 0]; X)$ and $x = f(0)$ the inequality

$$\left\| \prod_{j=0}^{n-1} \mathcal{T}_0^{(s+jh)}(h) \mathcal{T}_d^{(s+jh)}(h) \begin{pmatrix} x \\ f \end{pmatrix} - \mathcal{T}(t, s) \begin{pmatrix} x \\ f \end{pmatrix} \right\| \leq \frac{C(t-s)^2}{n} (\|x\| + \|f\|_1 + \|f'\|_1)$$

holds for all $s \in [-T_0, T_0]$, $t \in [s, s + T_0]$ and for all $n \in \mathbb{N}$, where $h = \frac{t-s}{n}$.

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For the proof:

□ stability + telescoping argument +

□ **Local error estimate:**

For $T_0 > 0$ there is a constant $C > 0$ such that

$$\left\| \mathcal{T}_d^{(s)}(h) \mathcal{T}_0^{(s)}(h) \begin{pmatrix} x \\ f \end{pmatrix} - \mathcal{U}(s+h, s) \begin{pmatrix} x \\ f \end{pmatrix} \right\| \leq Ch^2 (\|x\| + \|f\|_1 + \|f'\|_1)$$

holds for all $h \in [0, 1]$, $s \in [-T_0, T_0]$ and $f \in W^{1,1}([-1, 0]; X)$, $x = f(0)$.

Special structure:

$$\mathcal{T}_0^{(r)}(t) := \begin{pmatrix} V^{(r)}(t) & 0 \\ V_t^{(r)} & L(t) \end{pmatrix} \quad \text{and} \quad \mathcal{T}^{(r)}(t) = \begin{pmatrix} I & t\Phi(r) \\ 0 & I \end{pmatrix},$$

WHERE:

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□ The local error can be directly estimated

Delay equation:

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Splitting Type 1

$$\mathcal{G} := \begin{pmatrix} B & \Psi \\ 0 & \frac{d}{d\sigma} \end{pmatrix} = \begin{pmatrix} B & 0 \\ 0 & 0 \end{pmatrix} + \begin{pmatrix} 0 & \Psi \\ 0 & \frac{d}{d\sigma} \end{pmatrix} = \mathcal{A}_0 + \mathcal{A}_d$$

Splitting Type 2

$$\mathcal{G}(t) := \begin{pmatrix} B(t) & \Phi(t) \\ 0 & \frac{d}{d\sigma} \end{pmatrix} = \begin{pmatrix} B(t) & 0 \\ 0 & \frac{d}{d\sigma} \end{pmatrix} + \begin{pmatrix} 0 & \Phi(t) \\ 0 & 0 \end{pmatrix} = \mathcal{B}_0 + \mathcal{B}_d$$

result in a **first order** splitting

Thanks for listening!

