

### PROBLEM 1

As we know from given conditions for every  $t \geq 0$  there exists  $M(t)$  such that  $\|T_n(t)\| < M(t)$  for all  $n \in \mathbb{N}$ . Let us take  $t \geq 0$  arbitrary and write  $t = k + r$  with  $k \in \mathbb{N}$  and  $r \in [0, 1)$ . Then for all  $n \in \mathbb{N}$  we obtain

$$\begin{aligned} \|T_n(t)\| &\leq \|T_n(r)T_n(k)\| \leq \|T_n(r)\| \|T_n(1)\|^k \\ &\leq M^k(1) \|T_n(r)\| \leq (1 + M(1))^k \|T_n(r)\| \leq (1 + M(1))^t \|T_n(r)\|. \end{aligned}$$

By using the uniformly boundedness principle and the uniform convergence of  $T_n(r)f$  for  $r$  on compact intervals from  $[0, \infty)$  we conclude that

$$\sup_{r \in [0, 1)} \sup_{n \in \mathbb{N}} T_n(r) < \infty$$

Thus there exists  $M \geq 1$  such that  $\|T_n(r)\| \leq M$  for all  $n \in \mathbb{N}$  and  $r \in [0, 1)$ . Therefore we can continue the sequence of inequalities above and write

$$\|T_n(t)\| \leq \|T_n(r)T_n(k)\| \leq M(1 + M(1))^t = Me^{\omega t}$$

with  $\omega = \log(1 + M(1))$ .

### PROBLEM 2

Let us fix an arbitrary  $f \in C_{(0)}([0, 1])$ . We have to prove that

$$(0.1) \quad \sum_{k=0}^{n-1} f\left(\frac{k}{n}\right) B_{n,k}(x) \rightarrow f(x), n \rightarrow +\infty$$

uniformly in  $x \in [0, 1]$ . Let us fix an arbitrary  $\varepsilon > 0$ . Then, there exists  $N \in \mathbb{N}$ :  $\forall n > N \forall x_1, x_2 \in [0, 1]: |x_1 - x_2| \leq \frac{1}{n} \implies |f(x_1) - f(x_2)| < \varepsilon$  ( $f$  is uniformly continuous).  $(\forall n > N) (\forall x \in [0, 1]) (\exists k \in \overline{1, n}): \frac{k-1}{n} \leq x \leq \frac{k}{n}$ . Then,

$$\begin{aligned} \left| \sum_{k=0}^{n-1} f\left(\frac{k}{n}\right) B_{n,k}(x) - f(x) \right| &= \left| (nx - k + 1) f\left(\frac{k}{n}\right) + (k - nx) f\left(\frac{k-1}{n}\right) - f(x) \right| = \\ &= \left| (nx - k) \left( f\left(\frac{k}{n}\right) - f\left(\frac{k-1}{n}\right) \right) + \left( f\left(\frac{k}{n}\right) - f(x) \right) \right| \leq 2\varepsilon. \end{aligned}$$

In order to obtain the last inequality we used that  $f$  is uniformly continuous,  $x \in \left[\frac{k-1}{n}, \frac{k}{n}\right]$  and triangle inequality.

### PROBLEM 3

We first prove that there is a constant  $K > 0$  with  $\|P_n\|, \|J_n\| \leq K$  for all  $n \in \mathbb{N}$ . We actually show that  $K = 1$ . Indeed,

$$\begin{aligned}\|P_n f\|_{X_n} &= \frac{1}{n} \sum_{k=1}^n \left| n \int_{(k-1)/n}^{k/n} f \, dx \right| \leq \sum_{k=1}^n \int_{(k-1)/n}^{k/n} |f| \, dx = \|f\|_X, \\ \|J_n(y_1, \dots, y_n)\|_X &= \int_0^1 \left| \sum_{k=1}^n y_k \chi_{[(k-1)/n, k/n]}(x) \right| dx \\ &= \int_0^1 \sum_{k=1}^n |y_k| \chi_{[(k-1)/n, k/n]}(x) \, dx = \|(y_1, \dots, y_n)\|_{X_n}.\end{aligned}$$

The identity  $P_n J_n = I_n$  holds trivially.

Finally, let us show that the sequence  $J_n P_n f$  converges to  $f$  as  $n \rightarrow \infty$  in  $L^1$ -norm for all integrable functions  $f$ . We obtain the stated convergence for  $C([0, 1])$ -functions. Letting  $g \in C([0, 1])$  and applying the mean value theorem for integration yields

$$\begin{aligned}\left\| g(x) - n \sum_{k=1}^n \int_{(k-1)/n}^{k/n} g(t) \, dt \chi_{[(k-1)/n, k/n]}(x) \right\|_{L^1(0,1)} &= \int_0^1 \left| g(x) - \sum_{k=1}^n g(\xi_k) \chi_{[(k-1)/n, k/n]}(x) \right| dx \\ &= \sum_{k=1}^n \int_{(k-1)/n}^{k/n} |g(x) - g(\xi_k)| \, dx < \frac{\varepsilon}{3}.\end{aligned}$$

Here we used the uniform continuity of  $g$ . For each  $\varepsilon > 0$  and  $f \in L^1(0, 1)$  there exists  $g \in C([0, 1])$  such that  $\|f - g\|_{L^1(0,1)} < \frac{\varepsilon}{3}$ . Hence

$$\begin{aligned}\|J_n P_n f - f\|_{L^1(0,1)} &\leq \|f - g\|_{L^1(0,1)} + \|J_n P_n g - g\|_{L^1(0,1)} + \|J_n P_n(f - g)\|_{L^1(0,1)} \\ &< \frac{2\varepsilon}{3} + \|J_n P_n(f - g)\|_{L^1(0,1)}.\end{aligned}$$

To finish the proof let us evaluate the last term in the above inequality

$$\begin{aligned}\|J_n P_n(f - g)\|_{L^1(0,1)} &= \int_0^1 \left| n \sum_{k=1}^n \int_{(k-1)/n}^{k/n} (f - g)(t) \, dt \chi_{[(k-1)/n, k/n]}(x) \right| dx \\ &= \int_0^1 n \sum_{k=1}^n \left| \int_{(k-1)/n}^{k/n} (f - g)(t) \, dt \right| \chi_{[(k-1)/n, k/n]}(x) \, dx = \sum_{k=1}^n \left| \int_{(k-1)/n}^{k/n} (f - g)(t) \, dt \right| < \frac{\varepsilon}{3}.\end{aligned}$$

PROBLEM 4

We have to consider the general case in Proposition 3.10. Let us again start by fixing some  $t_0 > 0$ . Then for all  $t \in [0, t_0]$  we obtain

$$\begin{aligned} (T_n(t)P_n - P_nT(t))A^{-1}f &= \underbrace{T_n(t)(P_nA^{-1} - A_n^{-1}P_n)}_f f \\ &+ A_n^{-1}(T_n(t)P_n - P_nT(t))f + \underbrace{(A_n^{-1}P_n - P_nA^{-1})T(t)}_f f \end{aligned}$$

Using the stability assumption we conclude that the first and the last term of this sum converge to zero in the operator norm and

$$\begin{aligned} \|T_n(t)(P_nA^{-1} - A_n^{-1}P_n)f\| &\leq Me^{\omega t_0}\|P_nA^{-1} - A_n^{-1}P_n\|\|f\| \\ \|(A_n^{-1}P_n - P_nA^{-1})T(t)f\| &\leq Me^{\omega t_0}\|P_nA^{-1} - A_n^{-1}P_n\|\|f\| \end{aligned}$$

Thus we now focus on the middle term.

Observe that the function

$$[0, t] \ni s \mapsto T_n(t-s)A_n^{-1}P_nT(s)A^{-1}h \in X$$

is differentiable and its derivative is

$$\begin{aligned} \frac{d}{ds}(T_n(t-s)A_n^{-1}P_nT(s)A^{-1}h) &= T_n(t-s)(-A_nA_n^{-1}P_nT(s) + A_n^{-1}P_nT(s)A)A^{-1}h \\ &= T_n(t-s)(A_n^{-1}P_n - P_nA^{-1})T(s)h. \end{aligned}$$

Hence, the fundamental theorem of calculus yields

$$A_n^{-1}(P_nT(t) - T_n(t)P_n)A^{-1}h = \int_0^t T_n(t-s)(A_n^{-1}P_n - P_nA^{-1})T(s)h ds$$

holds for all  $h \in X$  and  $t > 0$ . Using this obtain the inequality

$$\begin{aligned} \|A_n^{-1}(T_n(t)P_n - P_nT(t))A^{-1}h\| &\leq \int_0^t Me^{\omega(t-s)}\|A_n^{-1}P_n - P_nA^{-1}\|\|T(s)h\| ds \\ &\leq t_0M^2e^{\omega t_0}\|A_n^{-1}P_n - P_nA^{-1}\|\|h\|. \end{aligned}$$

Taking into account all obtained estimates, we conclude that for  $g \in D(A^2)$  we can introduce  $f = Ag$  and  $h = Af$  to get that

$$\|T_n(t)P_n g - P_nT(t)g\| \leq \|A_n^{-1}P_n - P_nA^{-1}\|M^2e^{\omega t_0}(t_0M\|A^2g\| + 2\|Ag\|).$$

Observing that  $\|Ag\| \leq \|A^{-1}\|\|A^2g\|$  from the last inequality we obtain the desired estimate.

PROBLEM A. 1

Let us put  $\Delta := \Delta x = \Delta y = \frac{\pi}{N}$ ,  $N \in \mathbb{N}$ . We'll use the denotation  $w_{i,j}(t) := w(t, x_i, y_j) := w(t, i\Delta x, j\Delta y)$ . The spatially discretised problem

has the form:

$$(0.2) \quad \frac{d}{dt} w_{ij}(t) = \frac{w_{i+1,j}(t) - 2w_{i,j}(t) + w_{i-1,j}(t)}{(\Delta x)^2} + \frac{w_{i,j+1}(t) - 2w_{i,j}(t) + w_{i,j-1}(t)}{(\Delta y)^2},$$

$$i, j = 1, \dots, N-1$$

The boundary conditions take the form  $w_{0,j}(t) = w_{i,0}(t) = w_{i,N}(t) = w_{N,j}(t) = 0$ . Let us put  $W(t) = (\vec{w}_1(t), \vec{w}_2(t), \dots, \vec{w}_{N-1}(t))^\top$ , where  $\vec{w}_j(t) = (w_{1,j}(t), w_{2,j}(t), \dots, w_{N-1,j}(t))$ . System (0.2) can be represented in the form:

$$\frac{d}{dt} W(t) = M_{x,y} W(t),$$

where  $M_{x,y} = M_x + M_y$  is  $(N-1)^2 \times (N-1)^2$ -matrix and matrices  $M_x, M_y$  have the form:

$$(0.3) \quad M_x = \begin{pmatrix} M & 0 & \dots & 0 \\ 0 & M & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & M \end{pmatrix}, \quad M_y = \frac{1}{(\Delta y)^2} \begin{pmatrix} I_{-2} & I_1 & 0 & 0 & \dots & 0 \\ I_1 & I_{-2} & I_1 & 0 & \dots & 0 \\ 0 & I_1 & I_{-2} & I_1 & \dots & 0 \\ \vdots & \ddots & \ddots & \ddots & \ddots & \vdots \\ 0 & 0 & \dots & I_1 & I_{-2} & I_1 \\ 0 & 0 & \dots & 0 & I_1 & I_{-2} \end{pmatrix},$$

where  $M$  is the same matrix as in Appendix (formula (A.3)),  $I_1 = \text{diag}(1, 1, \dots, 1) \in \mathbb{R}^{(N-1) \times (N-1)}$ ,  $I_{-2} = (-2)\text{diag}(1, 1, \dots, 1) \in \mathbb{R}^{(N-1) \times (N-1)}$ . Matrix  $M_{x,y}$  can also be represented in the form:

$$(0.4) \quad M_{x,y} = \begin{pmatrix} \tilde{M} & I_1 & 0 & 0 & \dots & 0 \\ I_1 & \tilde{M} & I_1 & 0 & \dots & 0 \\ 0 & I_1 & \tilde{M} & I_1 & \dots & 0 \\ \vdots & \ddots & \ddots & \ddots & \ddots & \vdots \\ 0 & 0 & \dots & I_1 & \tilde{M} & I_1 \\ 0 & 0 & \dots & 0 & I_1 & \tilde{M} \end{pmatrix}, \quad \tilde{M} = \frac{1}{(\Delta)^2} \begin{pmatrix} -4 & 1 & 0 & 0 & \dots & 0 \\ 1 & -4 & 1 & 0 & \dots & 0 \\ 0 & 1 & -4 & 1 & \dots & 0 \\ \vdots & \ddots & \ddots & \ddots & \ddots & \vdots \\ 0 & 0 & \dots & 1 & -4 & 1 \\ 0 & 0 & \dots & 0 & 1 & -4 \end{pmatrix}$$

## PROBLEM A. 2

Our proof starts with the observation that  $A^{\frac{1}{2}}$  is symmetric and  $D(A) \subset D(A^{\frac{1}{2}})$ . Next, by means of the Cauchy inequality

$$\begin{aligned} 0 &= 2\langle Au, u \rangle - 2\langle f, u \rangle = 2\langle Au, w \rangle - 2\langle f, w \rangle = 2\langle A^{\frac{1}{2}}u, A^{\frac{1}{2}}w \rangle - 2\langle f, w \rangle \\ &\leq 2\|A^{\frac{1}{2}}u\| \|A^{\frac{1}{2}}w\| - 2\langle f, w \rangle \leq \|A^{\frac{1}{2}}u\|^2 + \|A^{\frac{1}{2}}w\|^2 - 2\langle f, w \rangle \\ &= \langle Au, u \rangle + \langle Aw, w \rangle - 2\langle f, w \rangle, \end{aligned}$$

where the equality holds only if  $A^{\frac{1}{2}}u = A^{\frac{1}{2}}w$ , hence if  $u = w$ , and the proof is complete.

### PROBLEM A.3

a) In this case we have basis functions  $\varphi_j = \sin jx$ . Thus  $A\varphi_j = -j^2 \sin jx$  and the elements of the matrix  $A_m$  are defined as

$$(A_m)_{jk} = \langle A\varphi_j, \varphi_k \rangle = \int_0^\pi (-j^2) \sin(jx) \sin(kx) dx = -jk \frac{\pi}{2} \delta_{jk}$$

b) As basis functions in this case do not belong to  $H^2(0, \pi)$ , the matrix  $A_m$  has to be defined by using the weak formulation, i.e.,

$$(A_m)_{jk} = - \left\langle \frac{d}{dx} \varphi_j, \frac{d}{dx} \varphi_k \right\rangle$$

$$= \begin{cases} 0 & \text{for } k < j - 1 \\ \int_{(j-1)\Delta x}^{j\Delta x} \left(\frac{1}{\Delta x}\right)^2 dx & \text{for } k = j - 1 \\ - \left( \int_{(j-1)\Delta x}^{j\Delta x} \left(\frac{1}{\Delta x}\right)^2 dx + \int_{j\Delta x}^{(j+1)\Delta x} \left(\frac{1}{\Delta x}\right)^2 dx \right) & \text{for } k = j \\ \int_{(j-1)\Delta x}^{j\Delta x} \left(\frac{1}{\Delta x}\right)^2 dx & \text{for } k = j + 1 \\ 0 & \text{for } k > j + 1 \end{cases}$$

$$= \begin{cases} 0 & \text{for } k < j - 1 \\ \frac{1}{\Delta x} & \text{for } k = j - 1 \\ -\frac{2}{\Delta x} & \text{for } k = j \\ \frac{1}{\Delta x} & \text{for } k = j + 1 \\ 0 & \text{for } k > j + 1 \end{cases}.$$

i.e.,  $A_m = \frac{1}{\Delta x} \text{tridiag}(1, -2, 1)$ .

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